

Leveraging Existing Data to Improve Fish Movement & Passage Analysis

The “ELAM” Approach

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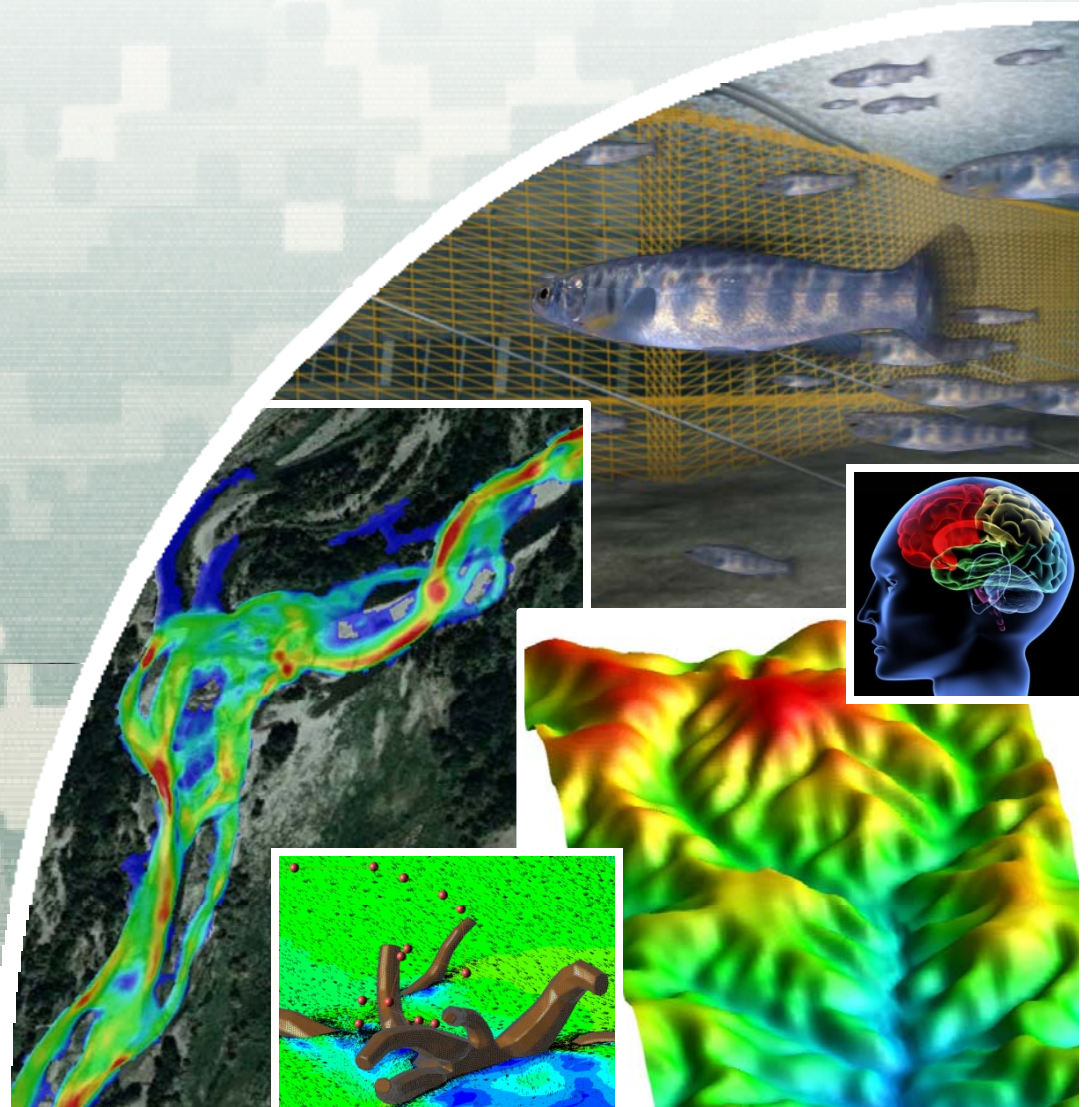
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*U.S. Army Engineer R&D Center
Vicksburg, Mississippi*



November 16, 2010

US Army Corps of Engineers
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The Problem Issue

(Why bother with yet another tool ?)

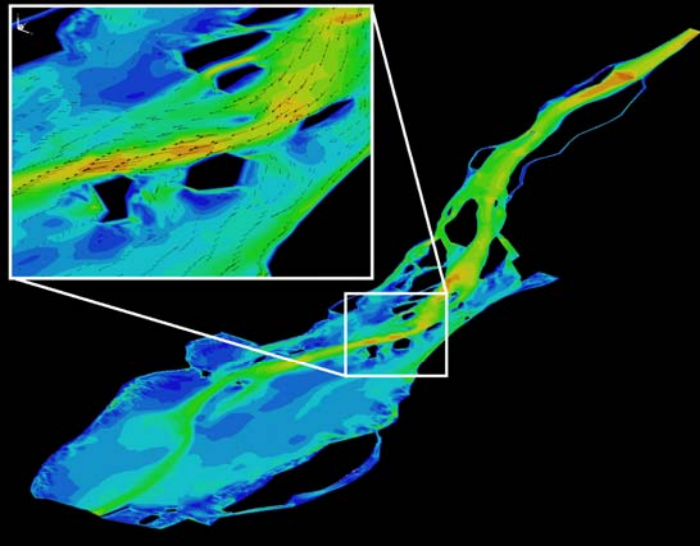


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Fish Movement & Habitat Analysis/Forecasting

(e.g., some suite of hydraulic and water quality variables)

(e.g., some description where to find fish or what fish are responding to)



Tractable ?

Generally, assumptions include:

- individual has perfect knowledge of the global environment,
- does not experience a change in internal state, and
- exhibits an all-or-nothing choice.

Mounting
Evidence

More flexible approach acknowledging:

- information limited due to varying sensory acuity and past experience,
- changes in internal state (e.g., physiology, learning) are important,
- decisions sometimes show irregularity and partial preferences, and
- continuous behavior adjustment in response to these factors.



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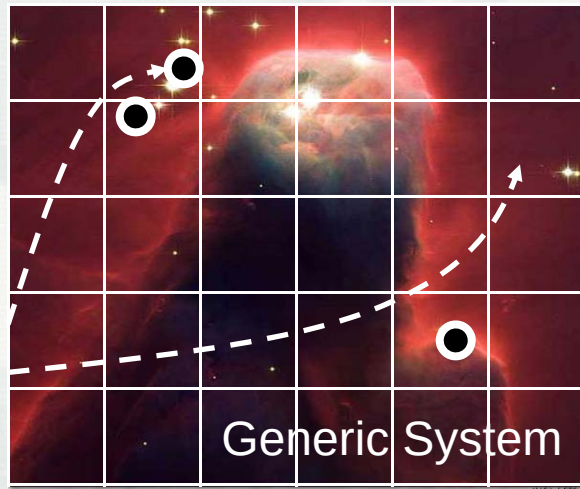
Our Solution Approach

(Integrate available data resources for a higher-fidelity approach)



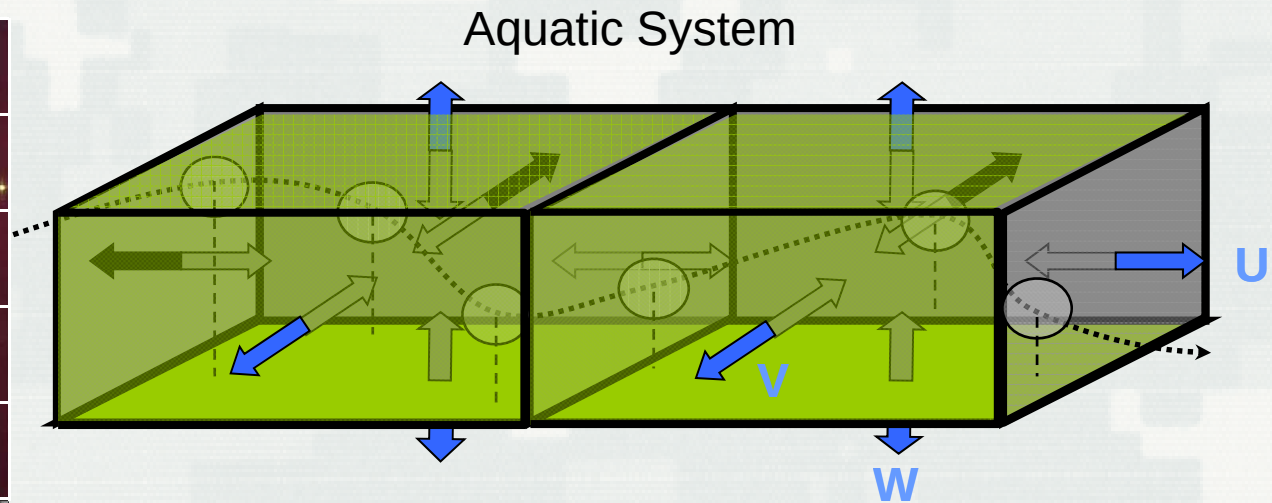
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The **Eulerian-Lagrangian-Agent Method (ELAM)**



Discretize it (Eulerian)

- Interstellar Dust
- Hydraulics / Water Quality
- Vegetation / Land Use



- Capturing Phenomena - small in time and space scale
- large/rare in time or space scale
 - internal state important

- 1) Eulerian framework: governs physical, hydraulic, water quality, terrestrial, & avian (atmospheric) domains,

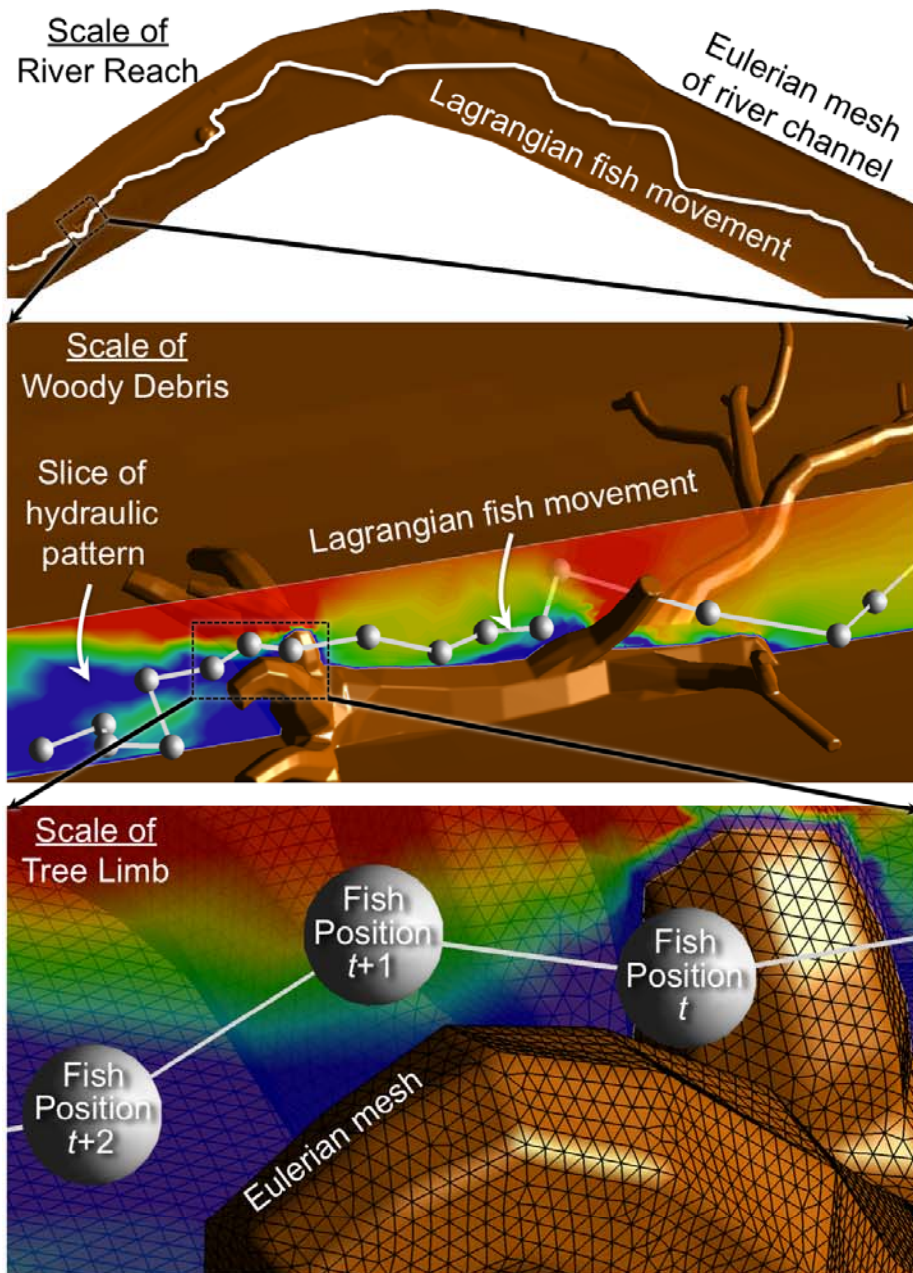
 |
 _____ → *mesh composed of nodes. Used by GIS and virtually all hydraulic and water quality models.*
- 2) Lagrangian framework: governs sensory perception and movement trajectories of individuals (fish, geese),

 |
 _____ → *continuous directional trajectory composed of discrete locations.*
- 3) agent framework: governs cognitive and memory domains responsible for behavior decisions of individuals.

 |
 _____ → *mathematics of animal perception for handling stimuli sensory processing, internal state, memory, response behavior, passage of time, and psychology.*



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Engineered Structure (Habitat)



Framework

Ecological Principle

Eulerian	Mesh composed of nodes used to describe pattern in landscape, hydraulics, and water quality.
Lagrangian	Continuous directional trajectory composed of discrete locations used to describe movement trajectories of individuals and perceptive range.
Agent	Biological mechanisms (internal state, cognition, physiology, bioenergetics) used to describe behavior response.

Engineered Structure (Dam)



Hydro Modeling is Readily Doable

(Needed basic data exists for most all systems)

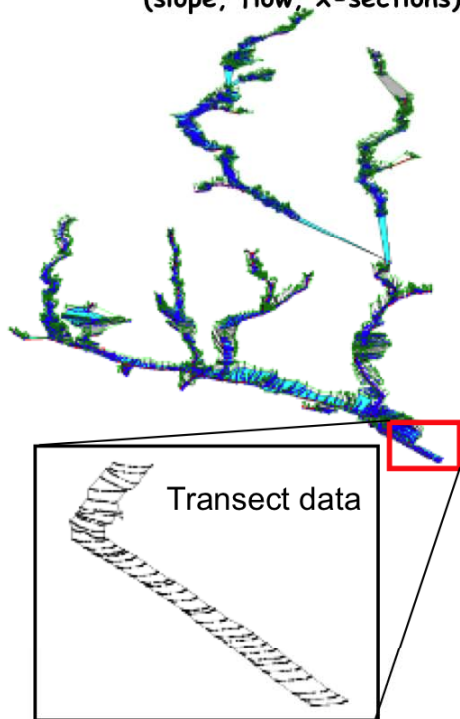


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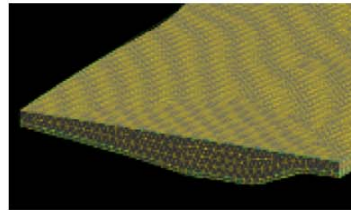
SHAPE – Stream Habitat Analyses Package →

MultiD high-fidelity ecological simulations from readily available data

(1) Start with existing, low-resolution model (e.g., HEC-RAS)
(slope, flow, x-sections)



(3) Develop multiD environment



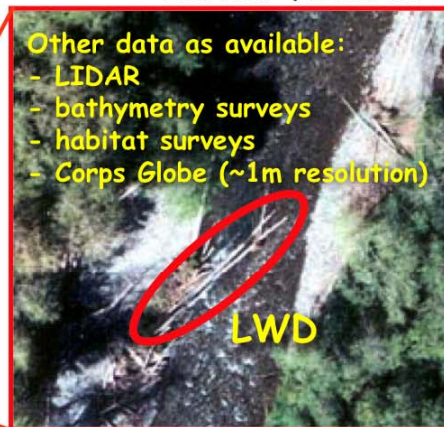
(4) Develop bathymetry between transects



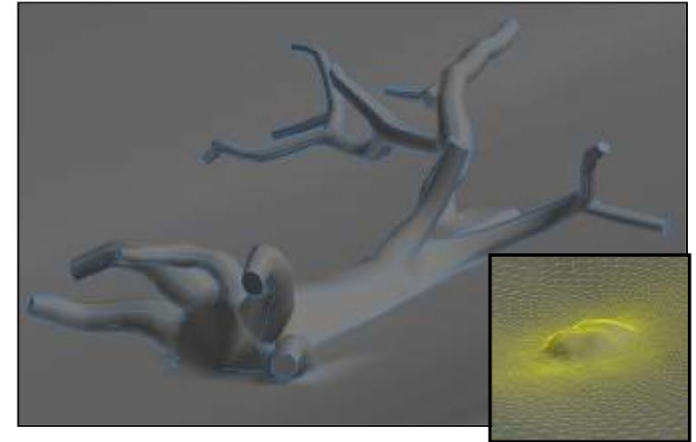
(2) Supplement w/aerial photos → Highlight important habitat features



Other data as available:
- LIDAR
- bathymetry surveys
- habitat surveys
- Corps Globe (~1m resolution)

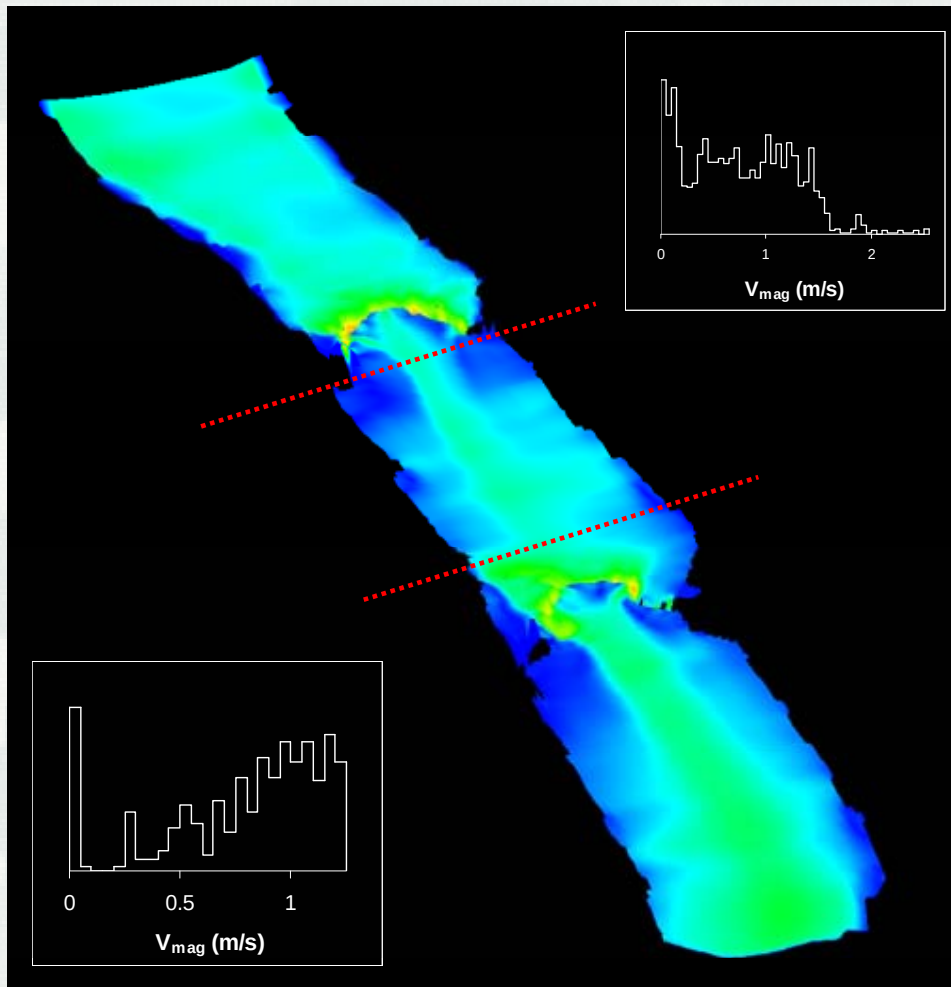


(5) Add important habitat features



Information in a Hydraulic Model

Velocity Magnitude



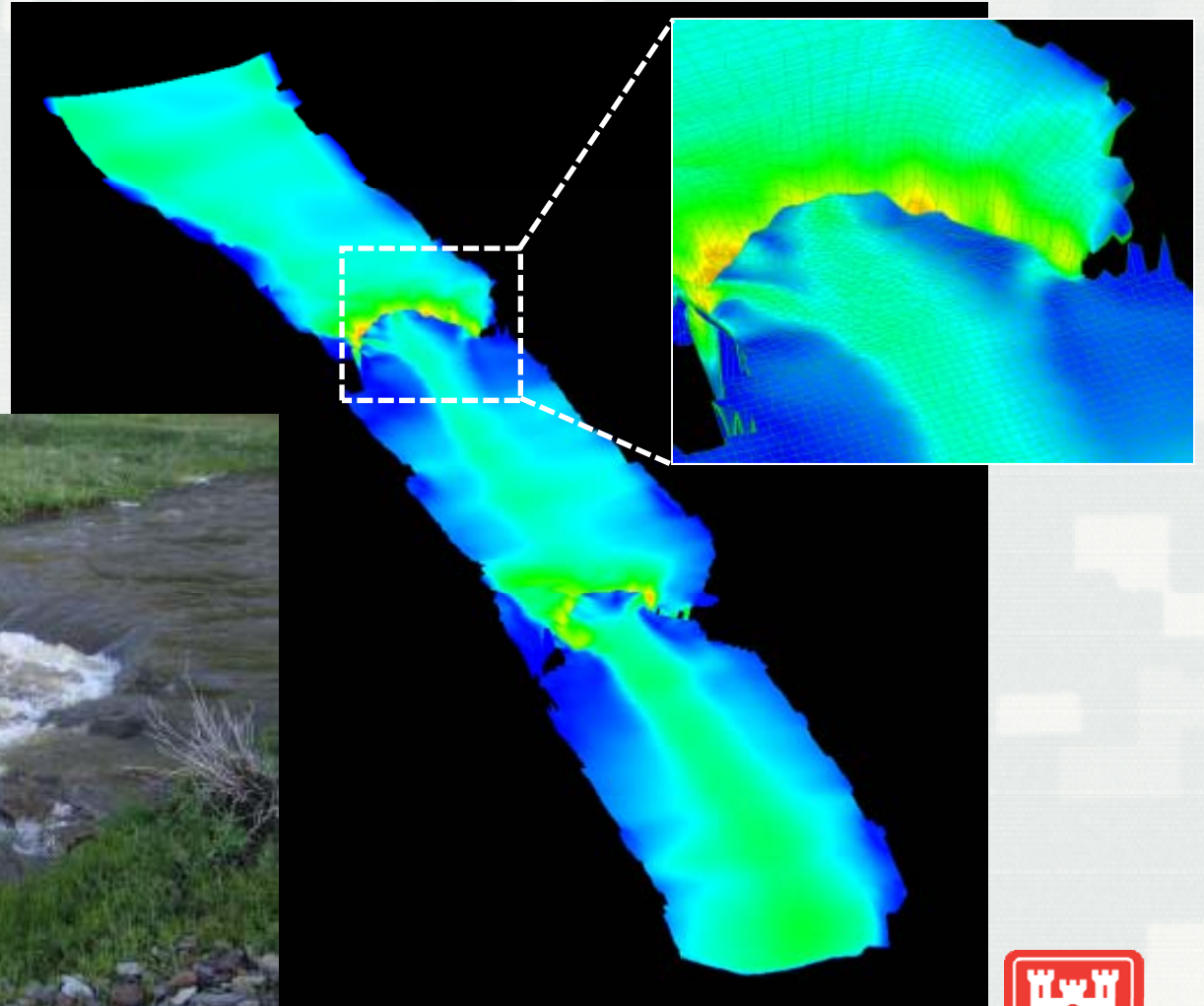
N = 1257
Mean = 0.749 m/s
S.D. = 0.514 m/s
Min = 0 m/s
Max = 2.542 m/s

N = 414
Mean = 0.793 m/s
S.D. = 0.363 m/s
Min = 0 m/s
Max = 1.238 m/s



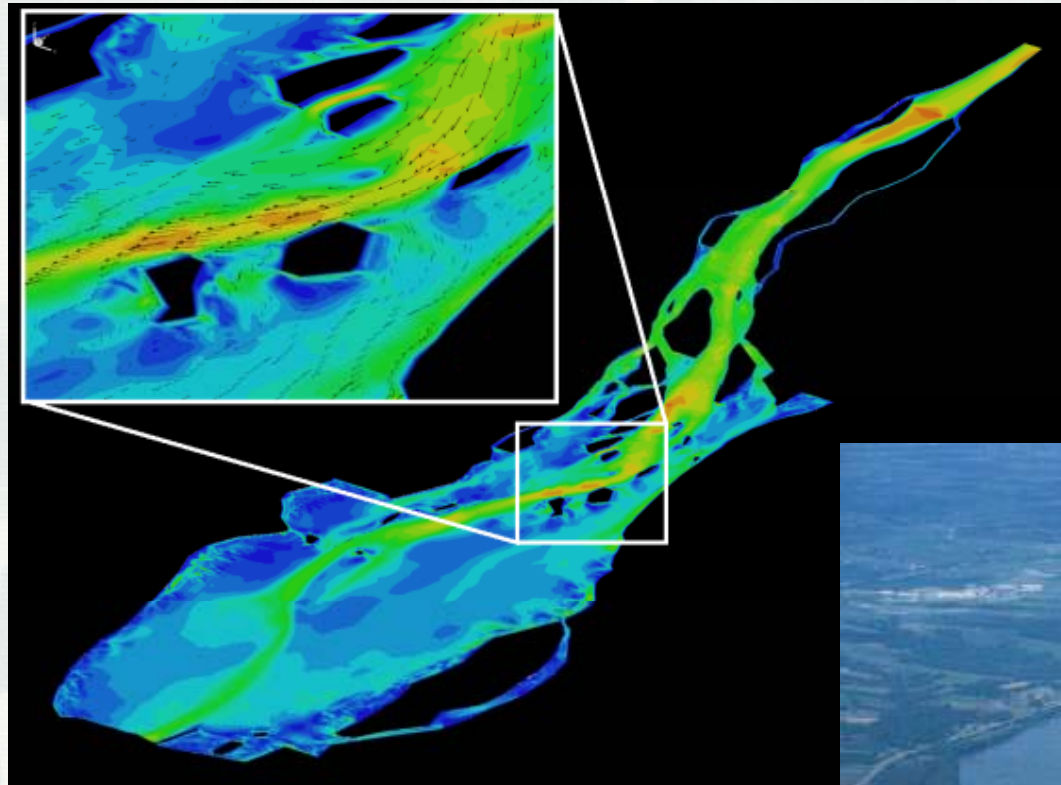
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Small Rivers



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Large Rivers



Mississippi River



Hydraulic model courtesy of Dr. Larry Weber
Photo courtesy of USGS

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Animal Decision-Making Behavior

(Fish on par with non-human primates in some cognitive tasks)



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Robust Phenomena

- Most biological systems adapt to different conditions & environments.
- Nervous system has mechanisms that use prior experience to predict future events.
- **These mechanisms can potentially support behavioral prediction.**
- Little known about which specific mechanisms are used.

SYSTEMS NEUROSCIENCE

NATURE | Vol 448 | 9 August 2007

Timing is everything

Phillip Larimer and Ben W. Strowbridge

Interactions among neurons in brain circuits underlie sensory perception and information storage. Work in locusts shows how the timing of different neuronal signals is synchronized to ensure effective communication.

ANIMAL BEHAVIOUR

Vol 445 | 22 February 2007

nature

Planning for breakfast

Sara J. Shettleworth

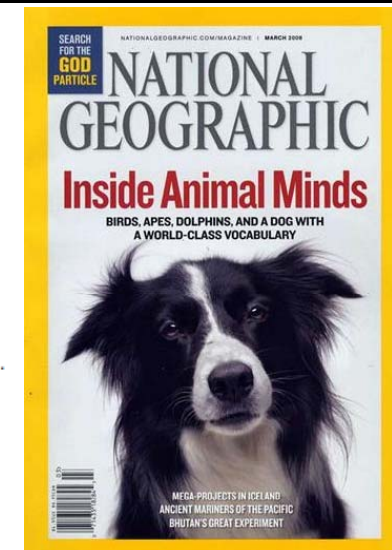
It is commonly believed that planning for the future is a skill unique to humans. Could other animals, even those as evolutionarily distant as western scrub-jays, share this skill with us?

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March 2008

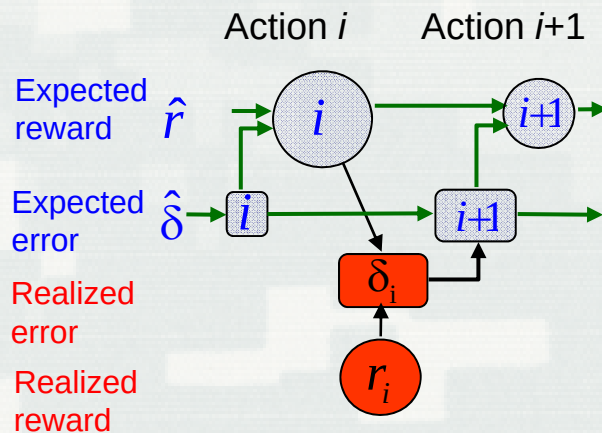
Inside Animal Minds

Brainy fellow creatures show that humans are not alone in their ability to invent, plan, or contemplate.



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Our Approach to Modeling Individual & Group Behavior in Complex Environments



Purpose:

- Identify/capture robust phenomena regarding how individuals detect/respond to environmental changes.

Product/Results:

- Concise, neurologically- and physiologically-realistic algorithm replicating fundamental & pervasive behavioral phenomena.

Payoff:

- A common “ELAM” model applicable to many fish species & contexts (passage, movement, habitat restoration).



1

Track Acclimatization
to Stimulus

$$I_{a_i}(t) = (1 - m_{a_i}) \cdot I_i(t) + m_{a_i} \cdot I_{a_i}(t-1)$$

2

Environmental
Stimulus Intensity

$$E_i(t) = I_i(t) - I_{a_i}(t)$$

Perceived

Present

Acclimated

3

Determine Perceived
Stimulus Events

$$e_i(t) = \begin{cases} 0 & \text{if } E_i(t) < k_i \\ 1 & \text{if } E_i(t) \geq k_i \end{cases}$$

4

Probability of Response

$$P_i(t) = (1 - m_i) \cdot e_i(t) + m_i \cdot P_i(t-1)$$

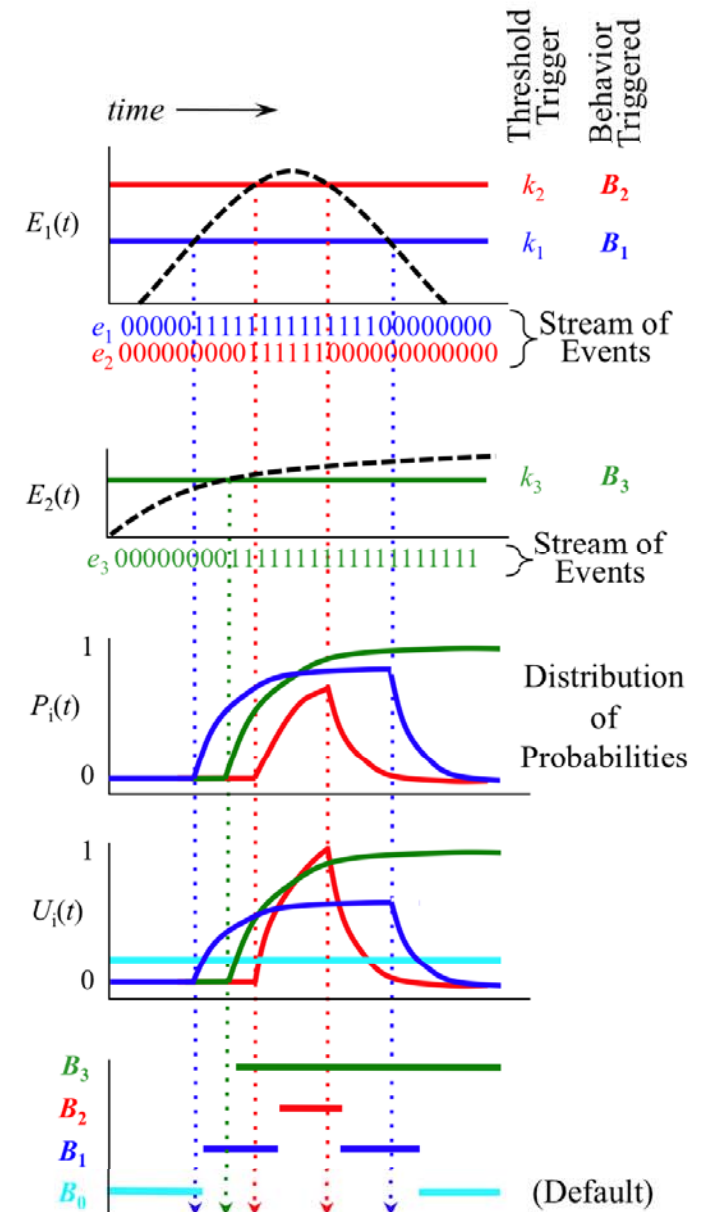
5

Utility (Weighted Probability) of Response

$$U_i(t) = P_i(t) \cdot u_i - C_i(t)$$

6

Behavior Repertoire



Testing the Approach

(At detailed and broad scales)



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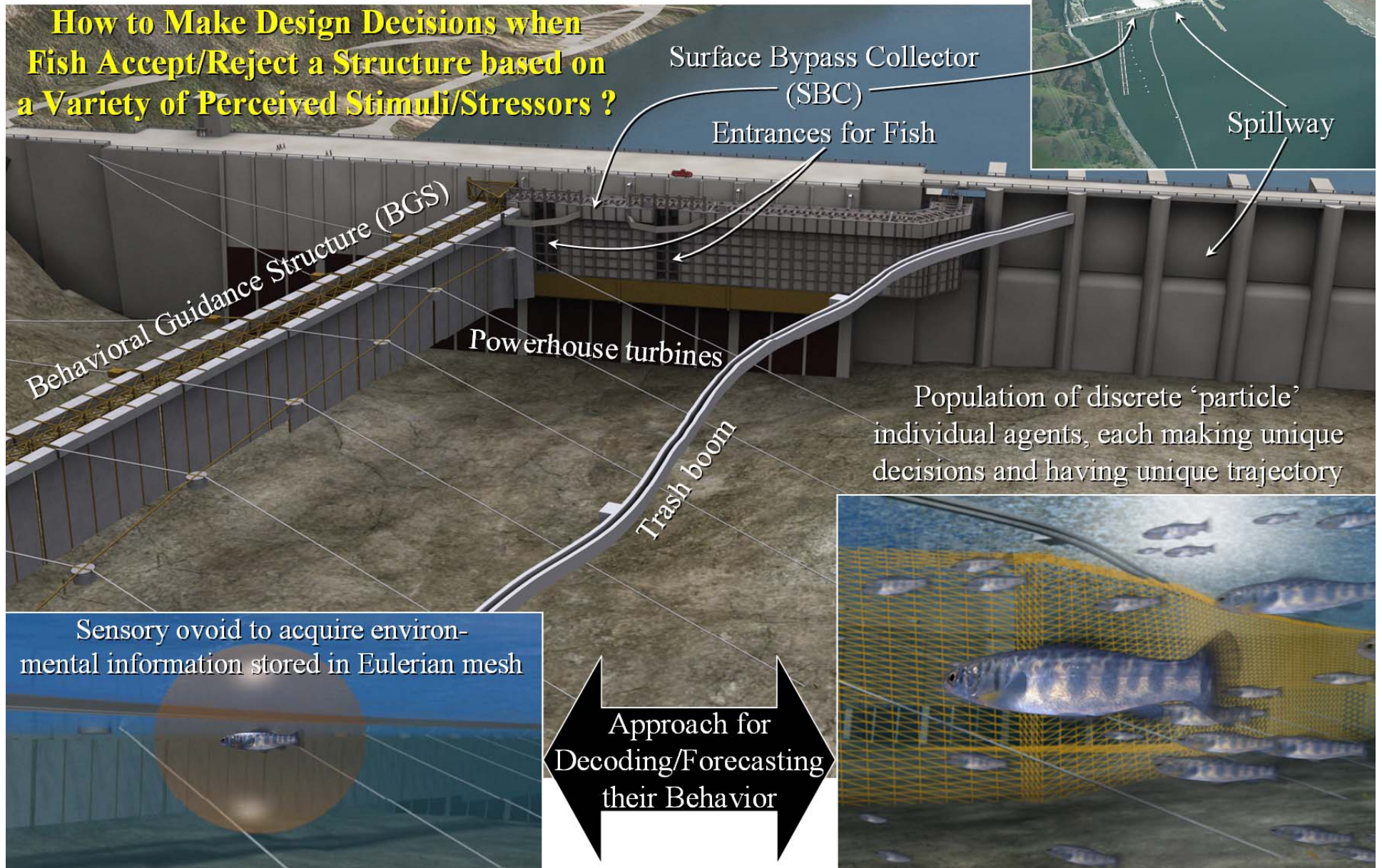
Why a PacNW Fish Passage Test ?

- Approach *not specific* to fish passage
 - ...but test data must come from somewhere
- PacNW data affords the *toughest* test:
 - Can modeled fish released a km upstream pass into meter-size openings at dam in correct proportions
 - Amount of fish data available in PacNW probably exceeds rest of world *combined*
- **USACE's opportunity:** sharpen knowledge of approach for apps where data is scant.

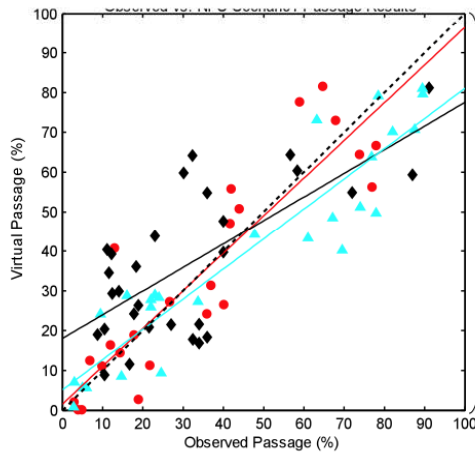
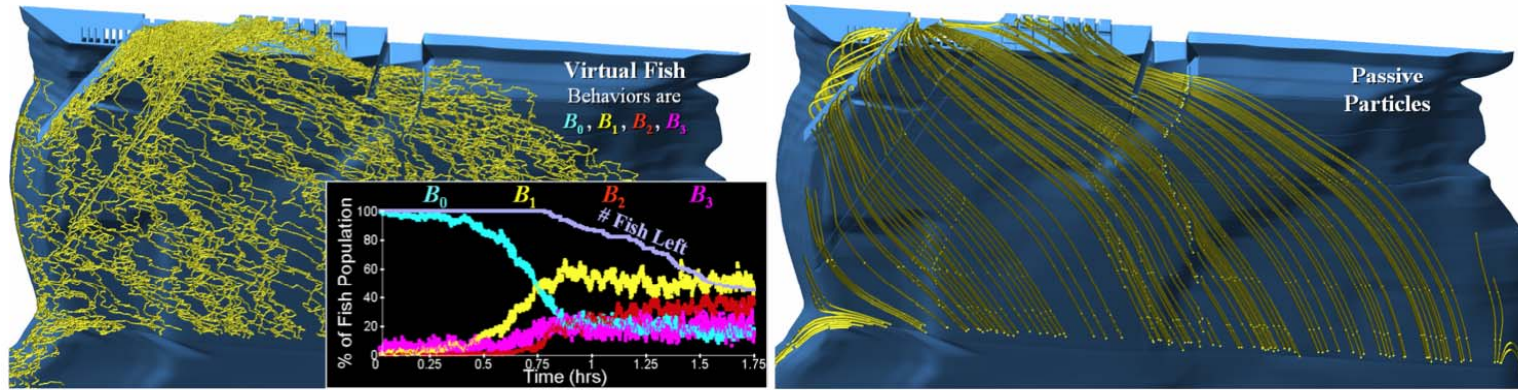


A Common Problem

How to Make Design Decisions when Fish Accept/Reject a Structure based on a Variety of Perceived Stimuli/Stressors ?



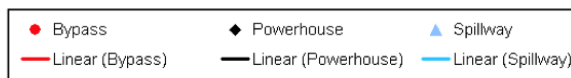
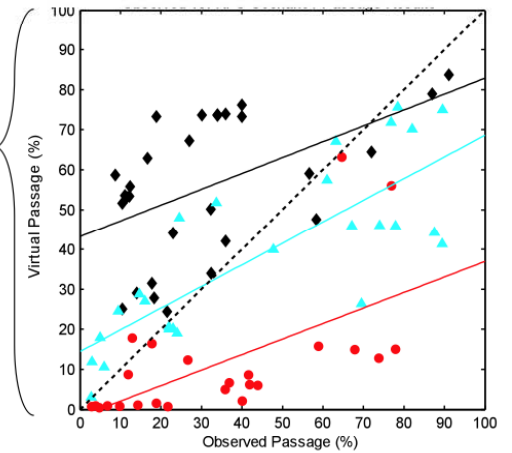
How Well Does it Work ?



Analysis Including: ALL					
Linear Model					Custom Metric
Slope	r^2	RMSE	Intercept	RMSE	Metric
Optimum	Optimum	Optimum	Optimum	Optimum	Optimum
1.0	1.0	0	0	0.0000	1.000
0.9484	0.8058	11.9105	1.5763		
0.5946	0.49	13.8216	18.0503	11.7837	0.777
0.759	0.8668	9.6191	5.1462		

Passive Particles

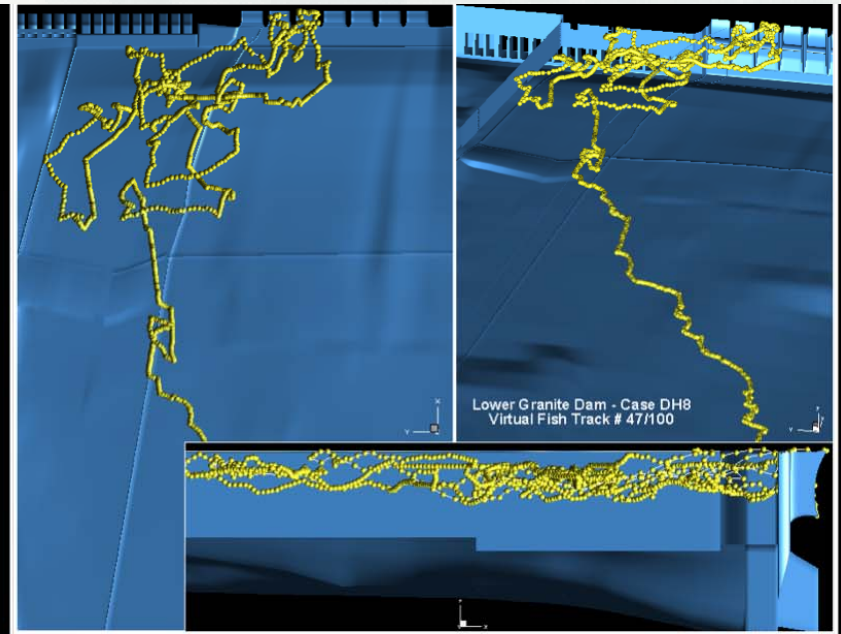
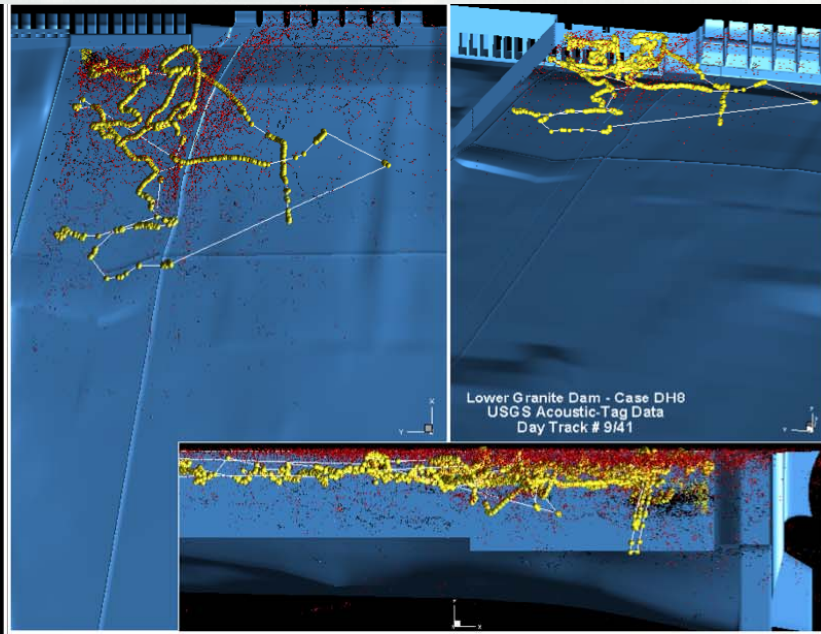
Analysis Including: ALL					
Linear Model					Custom Metric
Slope	r^2	RMSE	Intercept	RMSE	Metric
Optimum	Optimum	Optimum	Optimum	Optimum	Optimum
1.0	1.0	0	0	0	1.0
0.3875	0.3667	13.0279	-1.8218		
0.3965	0.2485	15.7099	43.2033	14.00903	0.418
0.5417	0.6346	13.2893	14.4342		



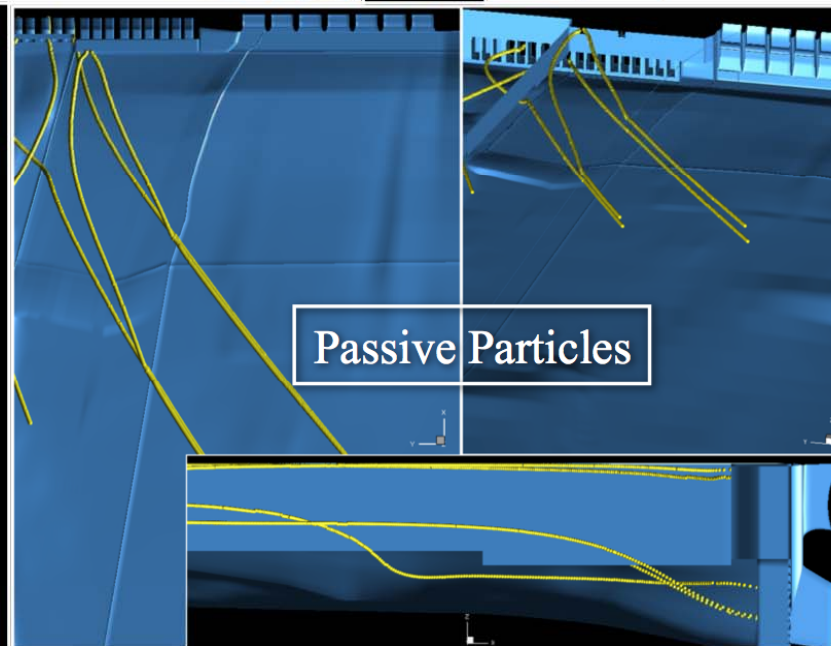
All Dams
(LGR, IHD, TDA, WAN, PRD)



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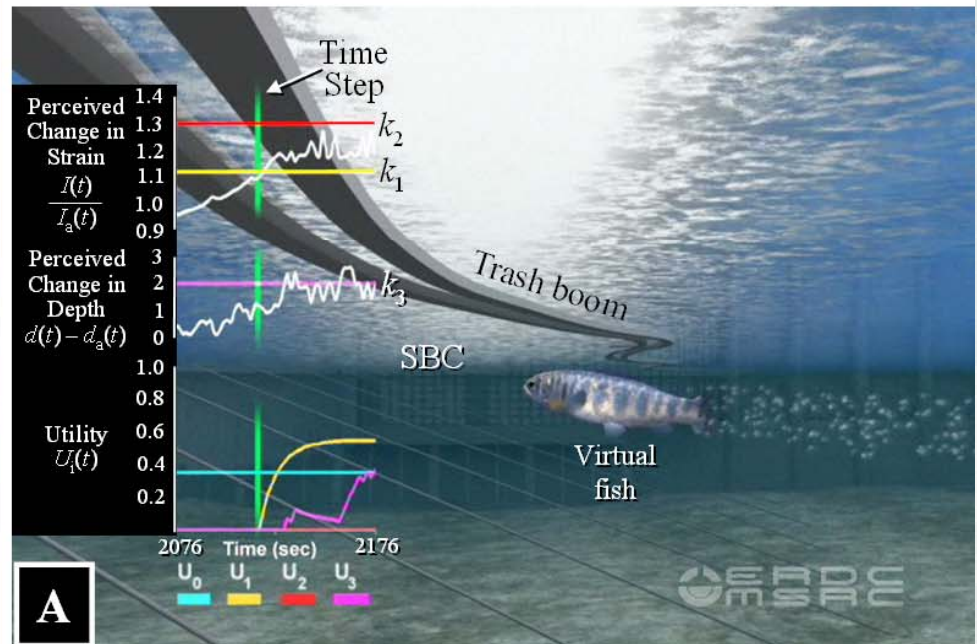
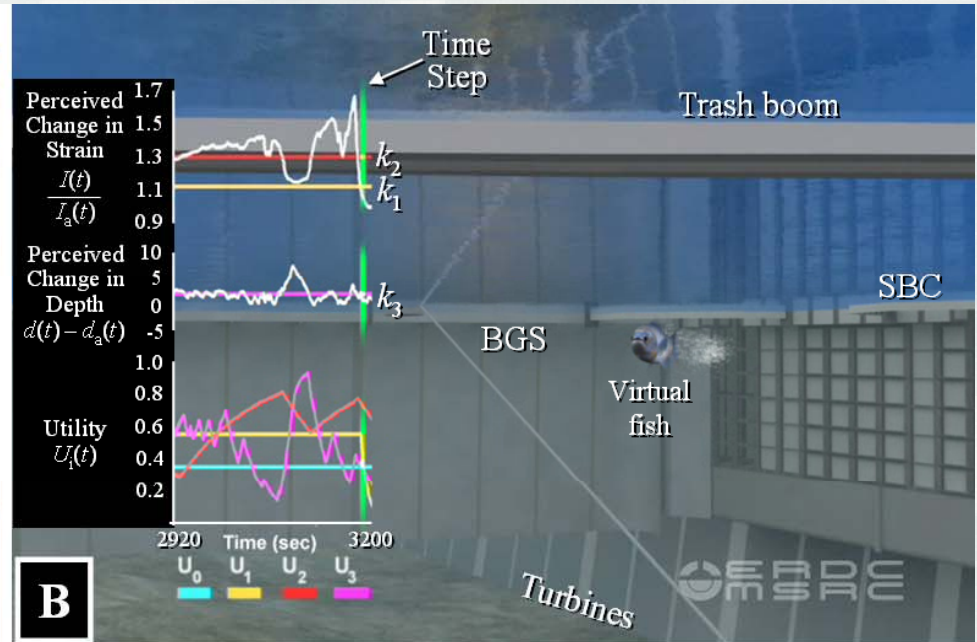
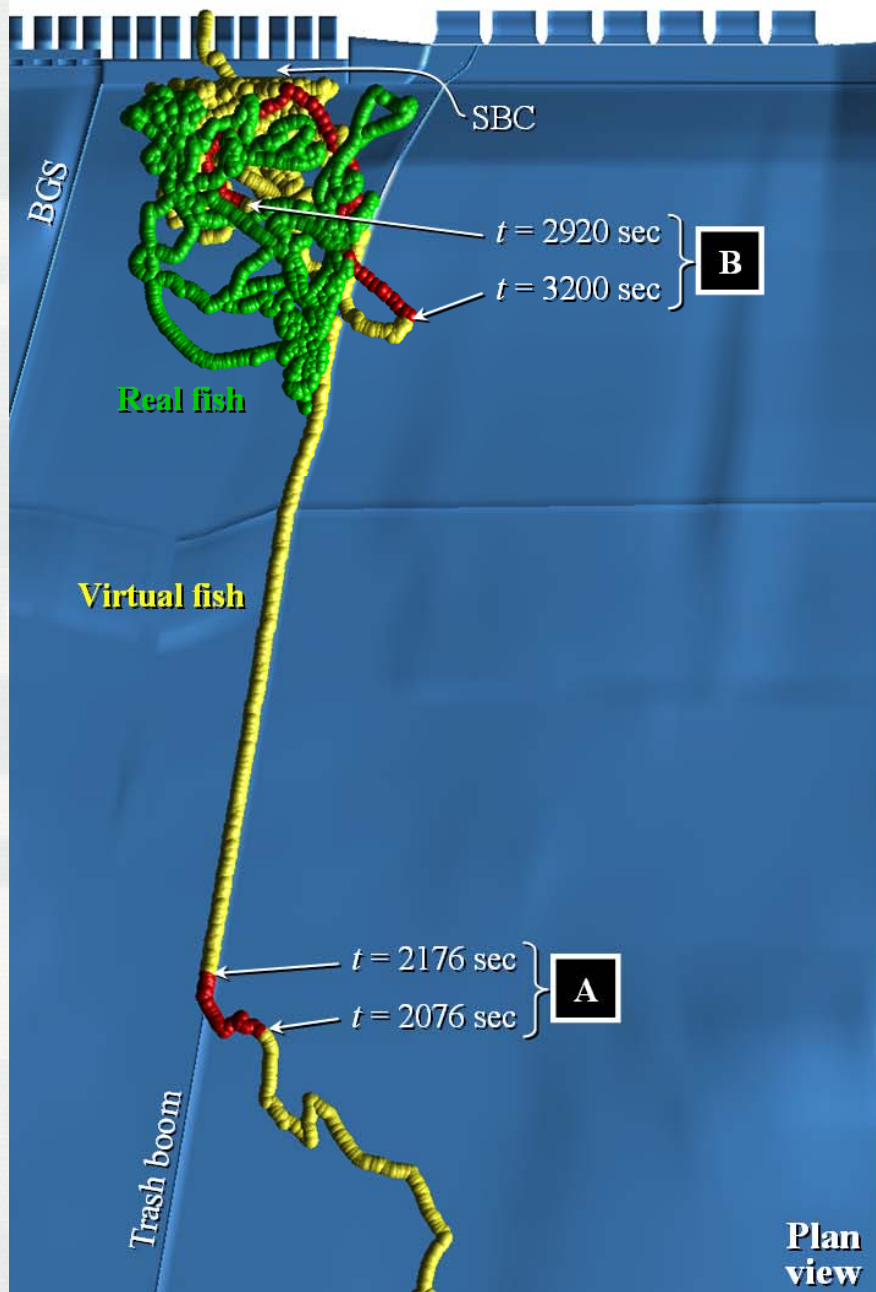
Acoustic-tagged
Juvenile Salmon
(USGS – Cash *et al.*, 2002)



Virtual
Juvenile Salmon
(ELAM Model)



Fish 'Agent' as it Moves thru Flow Field



Fish Swim Path Comparisons (3-D): Real vs. Model

<http://EL.erdc.usace.army.mil/emrrp/nfs/individualfish.html>

Is *hindcast* accuracy sufficient to *forecast* 'what if' future alternative scenarios ?



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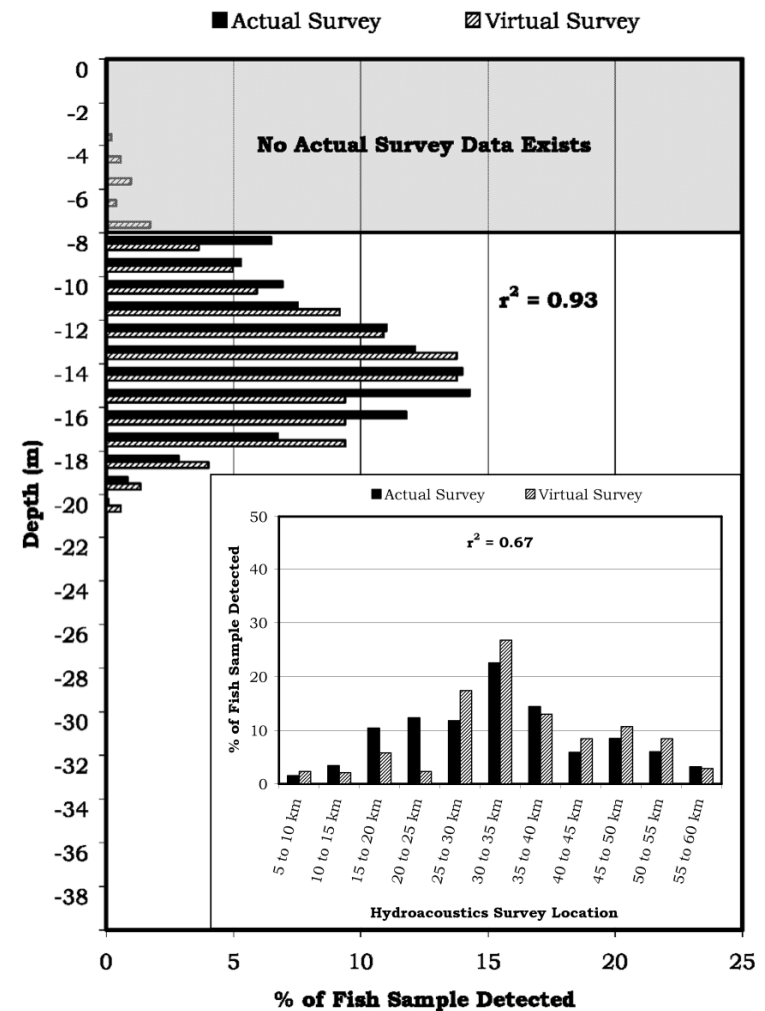
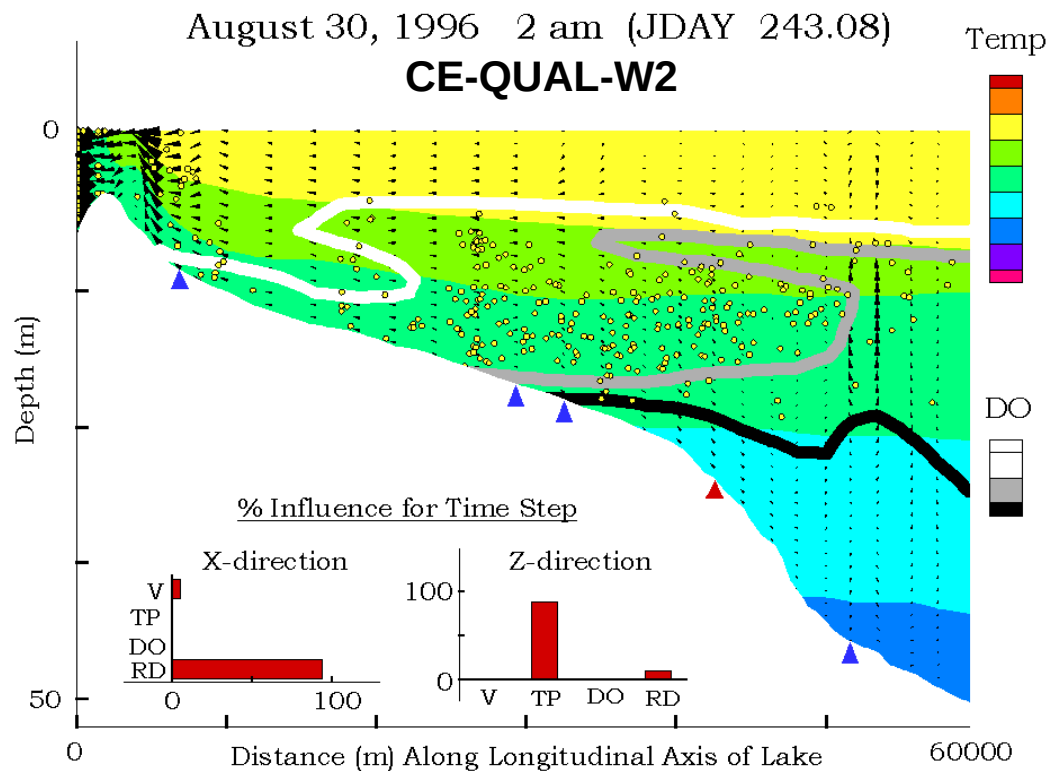
A Test from the Southeastern U.S.

- Advance system knowledge with simple data
 - Fish data from netting
 - Hydro/WQ patterns only at broad scales
- Operational impact on fish over many miles & months:
 - Can modeled fish released near beginning of year resemble distributions measured many months later
- Data may not need to be greater than that used to initially identify/observe problem in first place



Fish Movement over 60 km

- Temperature
- Dissolved oxygen
- Flow



Movement Comparisons (2-D): Modeled Fish vs. Particles

<http://EL.erdc.usace.army.mil/emrrp/nfs/fishhabitat.html>

Is *hindcast* accuracy sufficient to *forecast* 'what if' future alternative scenarios ?



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Observations of the Approach

- Can begin tackling behavior analysis within 5 hrs of hydraulic data arrival
- Performed well when model results developed prior to biological data being available
- Works for tested east- and west-coast species
- Works across years of observation
- Works at many different sites & scales



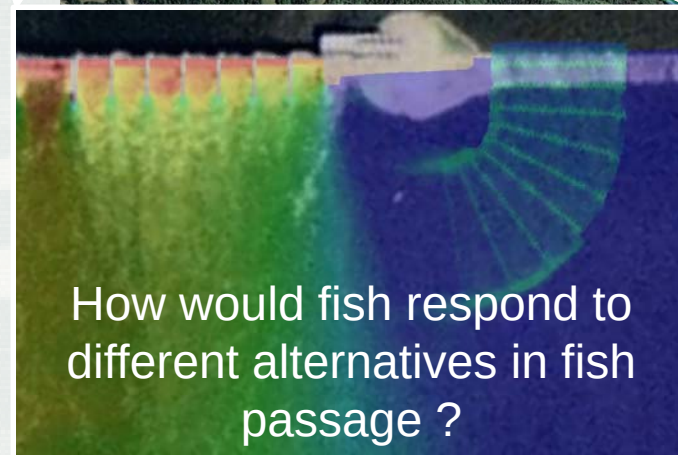
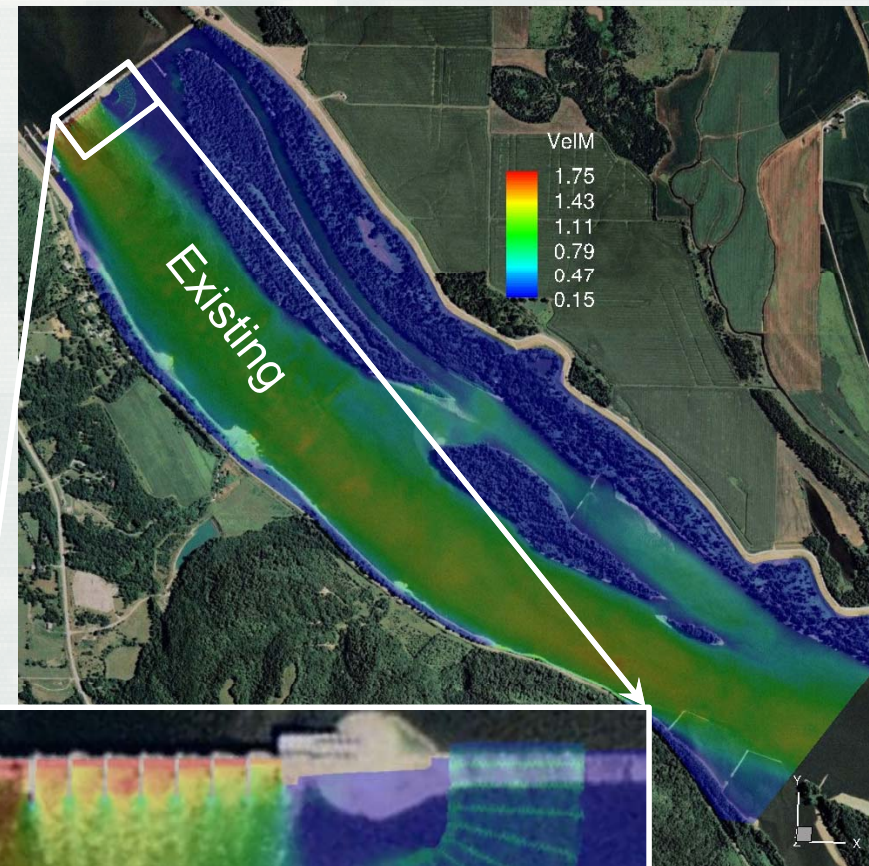
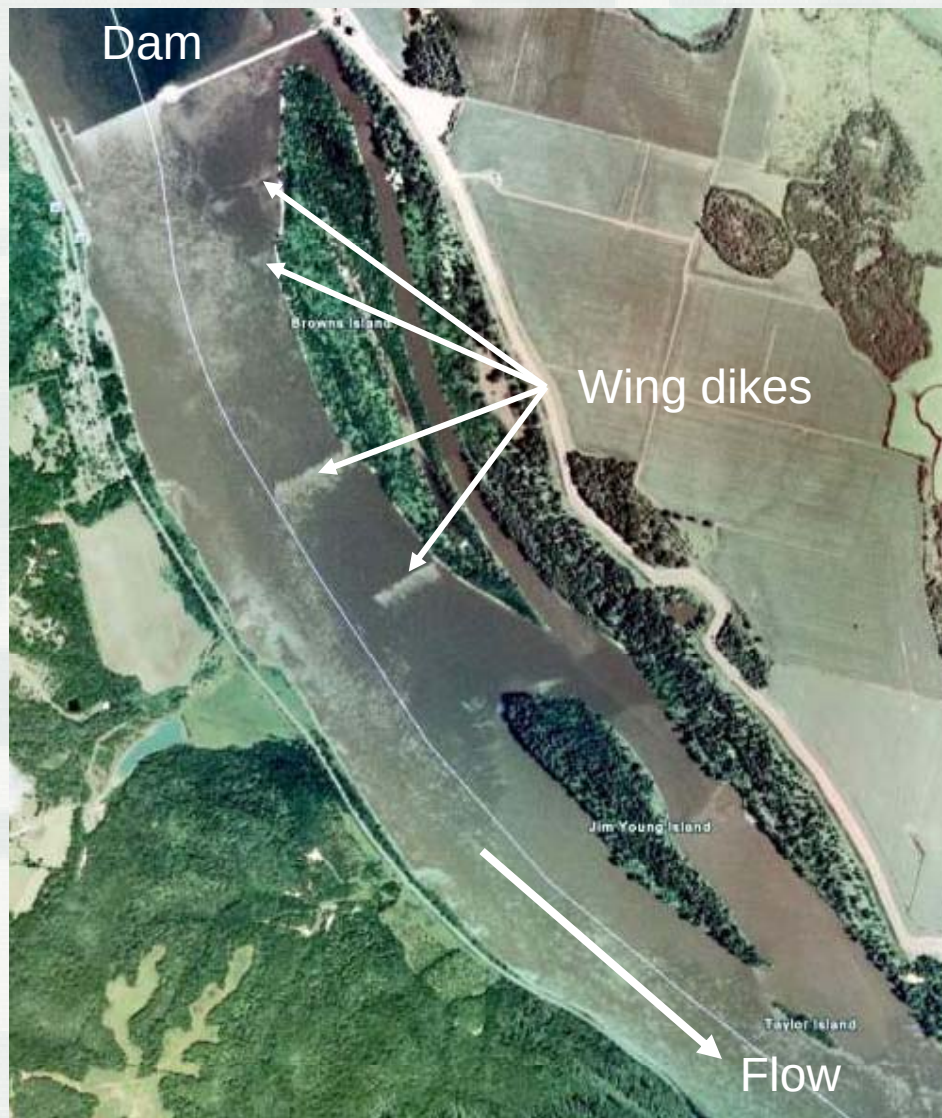
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Emerging Capability



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Mississippi River - Sturgeon

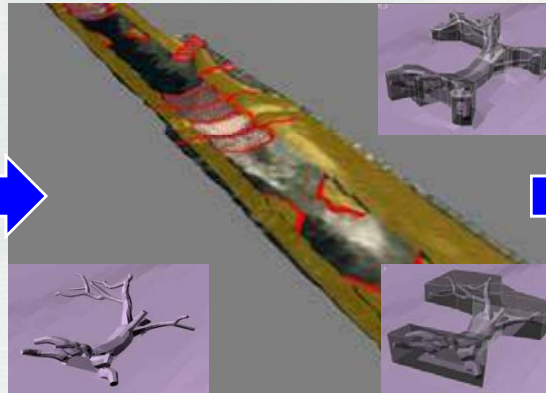


Stream Restoration – Dozens of Species

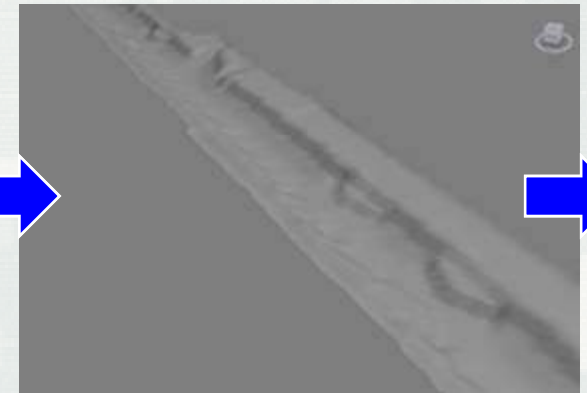
Project Site



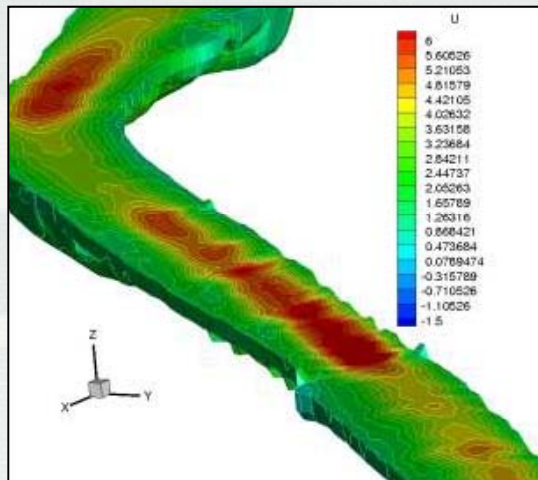
Conceptual Designs
(Alternatives)



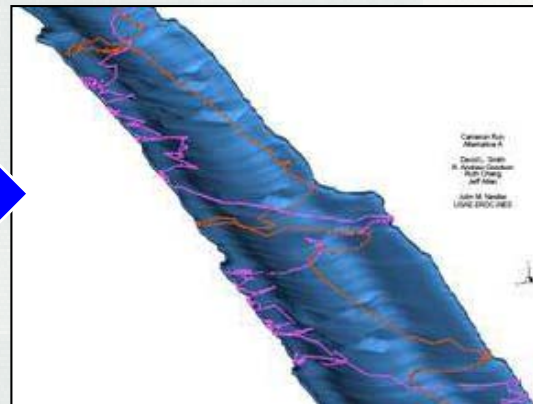
Models w/Features from
Conceptual Designs



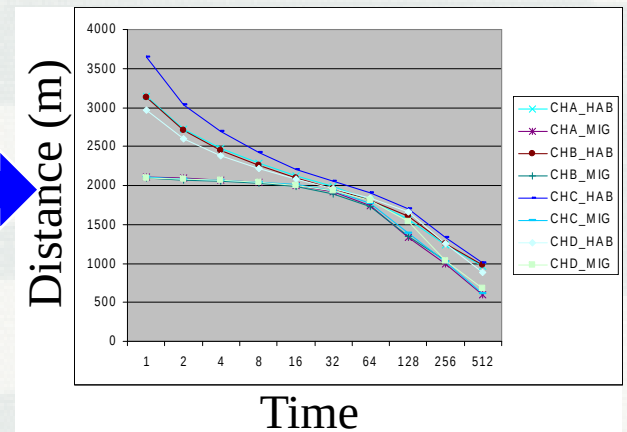
Hydraulic Output



ELAM Fish Movement



Assimilate into USACE Planning
Model of Alternatives
(e.g., HSI curves)

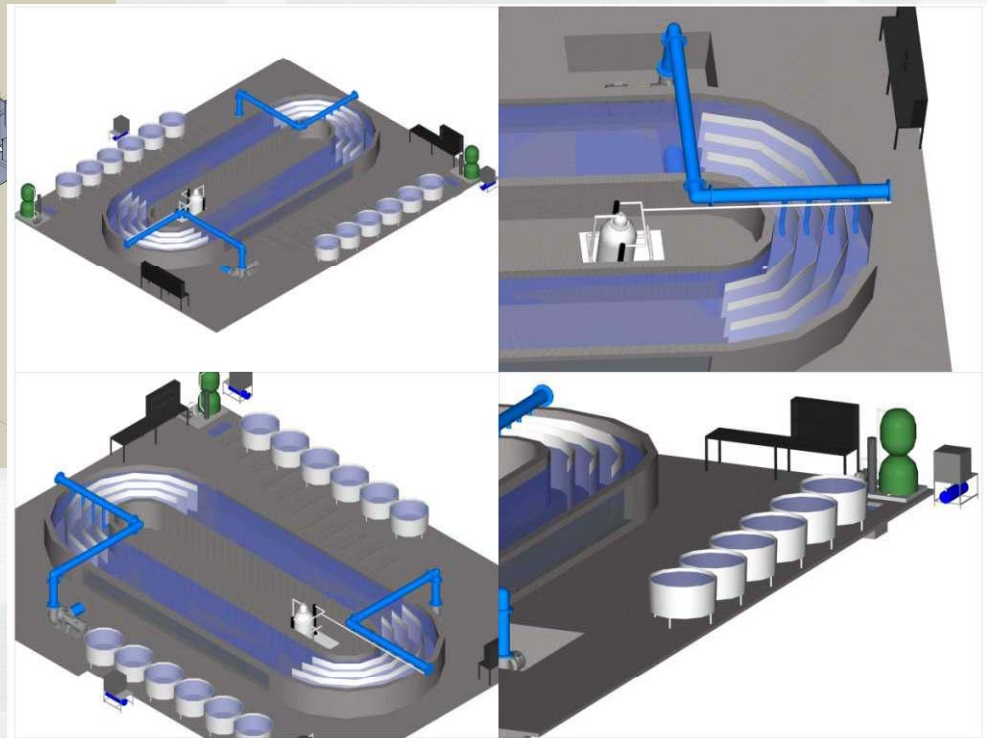
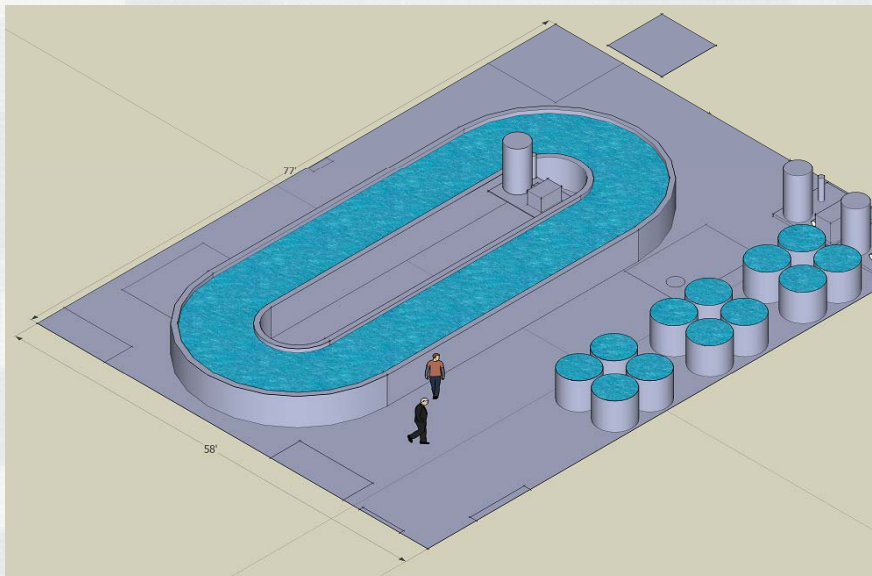


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Rapidly-deployable Behavior Analysis

Cognitive Ecology Research Flume

- \$1.3M facility w/movement tracking
- Probe multi-modal sensory stimuli response
- Response to different flow/WQ fields



The *Eulerian-Lagrangian-Agent Method (ELAM)*

When is the use of an *ELAM* important ?

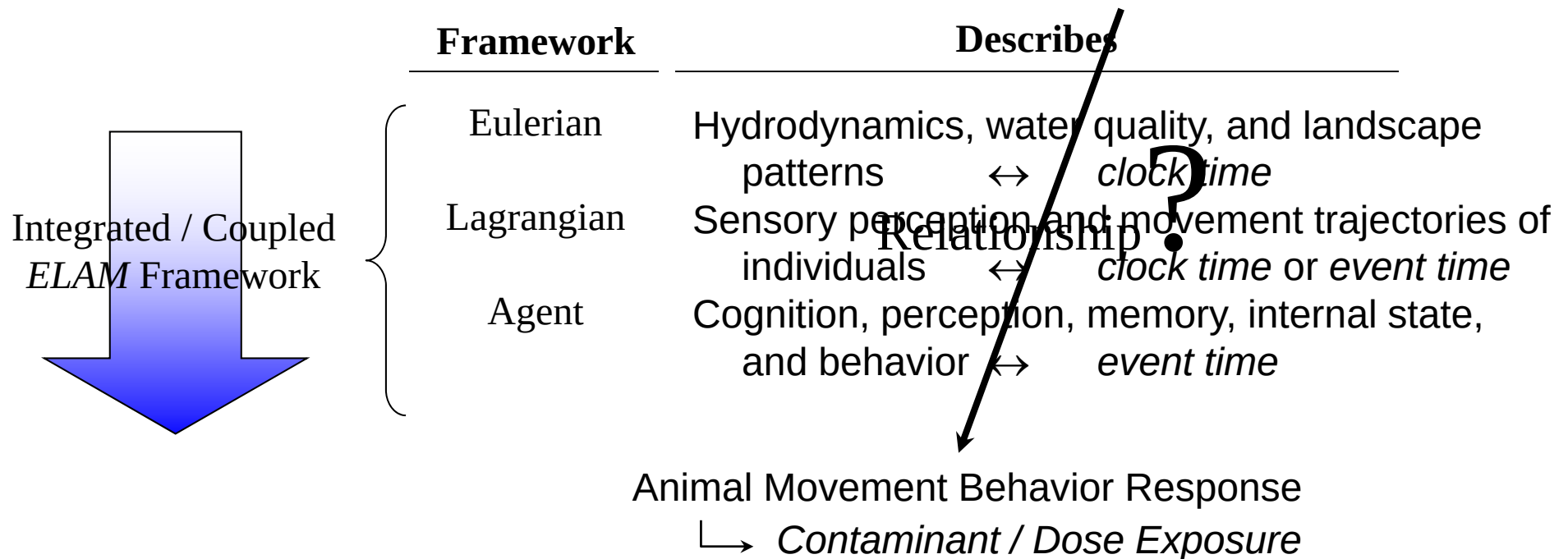
When movement behavior of highly mobile individuals influences 'success'

What is an *ELAM* ?

Integration of all 3 reference frameworks such that:

- temporal and spatial scaling of each process is optimally simulated,
- information is transformed as needed to meet requirements of linked processes,
- maximum fidelity to "real world" using "first principles" is achieved.

How to Assess Alternative Perturbations to Environmental Pattern



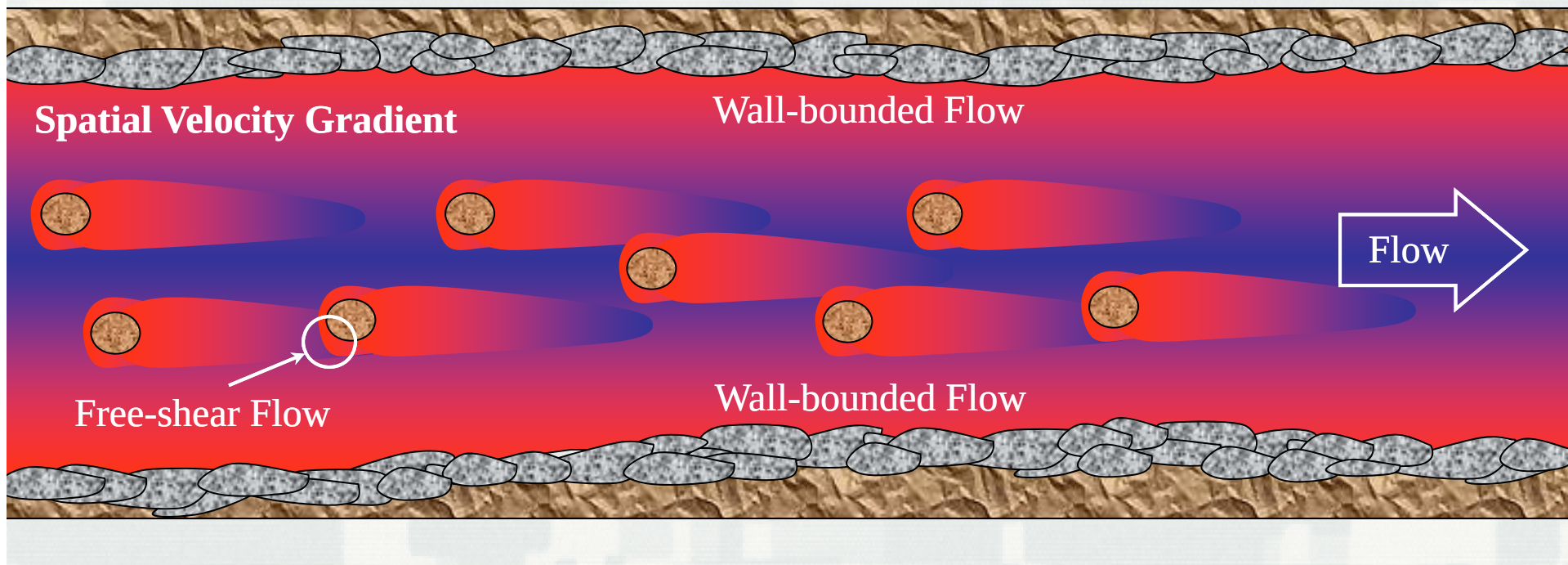
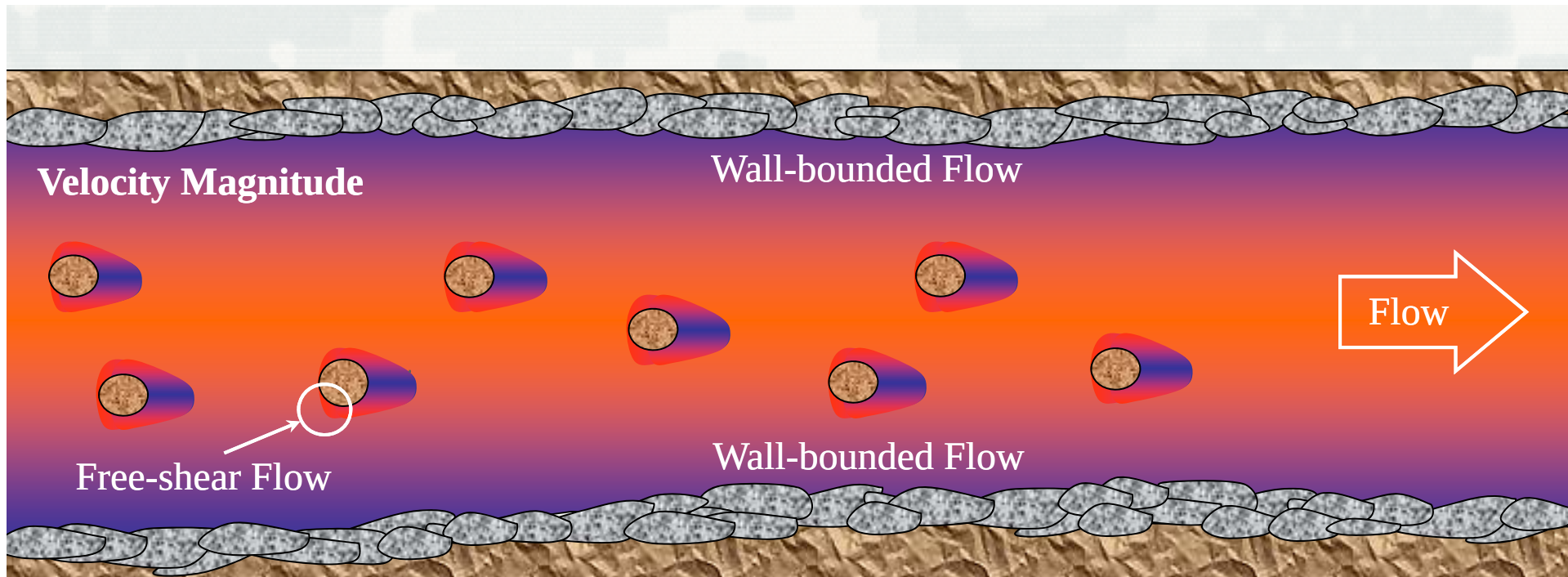
Model Accuracy & Quality of Engineering Guidance → Hypothesis Limited

- As mechanistic biological hypothesis develops/improves:
 - so does simulated behavior
 - so does decision-support

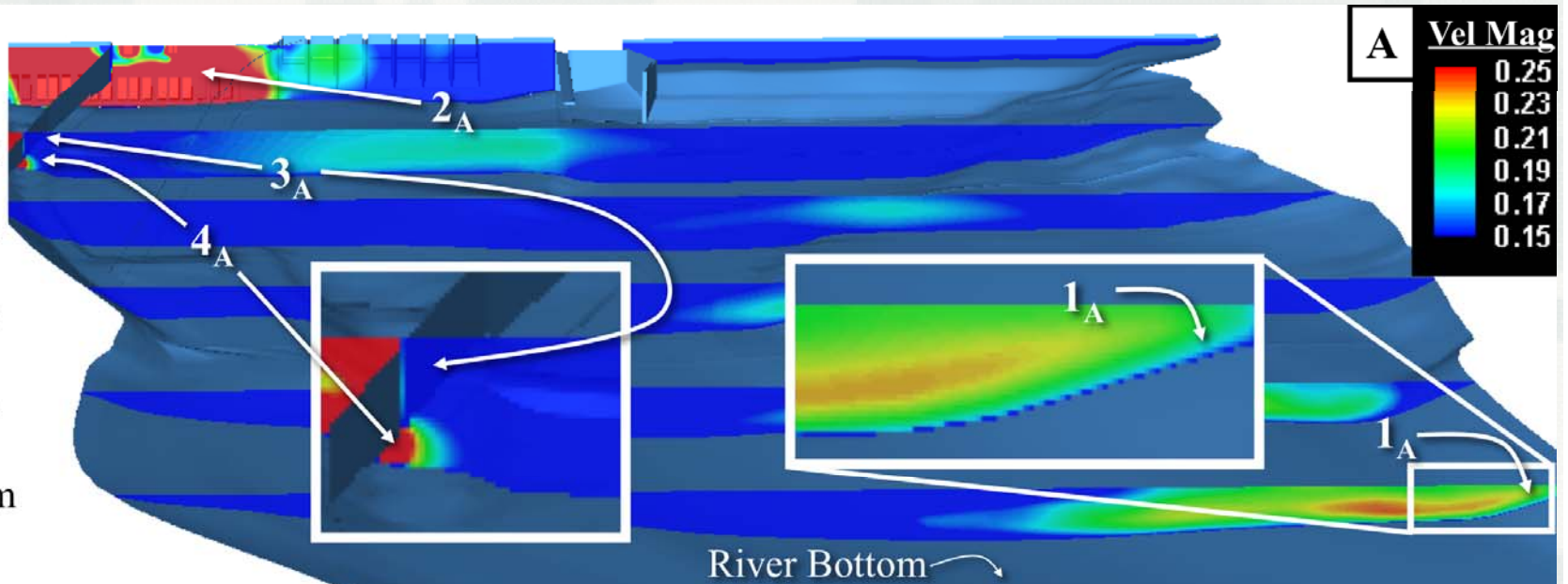
Questions / Comments / Criticisms ???



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Bypass = 55m
 x = 50m
 x = -200m
 x = -400m
 x = -650m
 x = -950m
 x = -1250m



Floating
 Wall
 (BGS)

Wall-Bounded Flow
 Locations: 1, 3
 Free-shear Flow
 Locations: 2, 4

